



PCT

INTERNATIONAL PRELIMINARY EXAMINATION REPORT

(PCT Article 36 and Rule 70)

Applicant's or agent's file reference 772-1017 ge	FOR FURTHER ACTION See Notification of Transmittal of International Preliminary Examination Report (Form PCT/IPEA/416)							
International application No.	International filing date	(day/month/year)	Priority date (day/month/year)					
PCT/EP2003/011729	23 October 2003	(23.10.2003)	28 October 2002 (28.10.2002)					
International Patent Classification (IPC) or national classification and IPC B25J 9/00								
Applicant KUKA SCHWEISSANLAGEN GMBH								
This international preliminary examination report has been prepared by this International Preliminary Examining Authority and is transmitted to the applicant according to Article 36.								
2. This REPORT consists of a total of	5 heets,	including this cover s	heet.					
This report is also accompanied by ANNEXES, i.e., sheets of the description, claims and/or drawings which have been amended and are the basis for this report and/or sheets containing rectifications made before this Authority (see Rule 70.16 and Section 607 of the Administrative Instructions under the PCT).								
These annexes consist of a total of sheets.								
3. This report contains indications rela	ating to the following iter	ns:						
I Basis of the report	I Basis of the report							
II Priority		٠						
III Non-establishment	of opinion with regard to	novelty, inventive st	ep and industrial applicability					
IV Lack of unity of in	vention							
- ' l 	V Reasoned statement under Article 35(2) with regard to novelty, inventive step or industrial applicability; citations and explanations supporting such statement							
VI Certain documents	Contain de summerte eited							
VII Certain defects in t	Contain defeats in the intermedianal condination							
VIII Certain observations on the international application								
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Date of submission of the demand		Date of completion of this report						
27 May 2004 (27.05.2004)		03 N	ovember 2004 (03.11.2004)					
Name and mailing address of the IPEA/EP		Authorized officer						
Facsimile No.		Telephone No.						

Translation



International application No.

PCT/EP2003/011729

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1. With	•	the elements of the international application:*	1			
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the international application was filed, unless otherwise indicated under this item. These elements were available or furnished to this Authority in the following language						
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5.		eport has been established as if (some of) the amendments had d the disclosure as filed, as indicated in the Supplemental Box (
* Replacement sheets which have been furnished to the receiving Office in response to an invitation under Article 14 are referred to in this report as "originally filed" and are not annexed to this report since they do not contain amendments (Rule 70.16 and 70.17).						
** Any	replacer	ment sheet containing such amendments must be referred to und	der item 1 and annexed to this report.			

ational application No. PCT/EP 03/011729		
PCT/EP	03/011729	

v.	Reasoned statement under Article 3st citations and explanations supporting	5(2) with regard to nove g such statement	elty, inventive step or industrial appli	cability;
1.	Statement			
	Novelty (N)	Claims	1-14	YES
		Claims		NO
	Inventive step (IS)	Claims	1-14	YES
		Claims		NO
	Industrial applicability (IA)	Claims	1-14	YES
		Claims		NO

2. Citations and explanations

1. This report refers to the following documents:

D1: DE 10102758 A (Volkswagen AG) - 25 July 2002

D2: WO 03034165 A (Cimac Automation Limited) - 24

April 2003

D3: US 4254433 A (General Motors Corporation) - 3

March 1981.

2. Claim 1: Novelty

Document D3 is considered to be the prior art closest to the subject matter of claim 1. It discloses (the references in parentheses relate to this document):

a method of machining workpieces in the shell of a car body, the workpieces (14) being conveyed along a transfer line (12) by a conveyor (10) and machined by a stationary multiaxis robot (16), the workpieces being conveyed continuously and machined by the robot during the conveyor movement, the robot in its axial movements being synchronized with the conveyor movement, and the movement and the position of the workpieces

being detected using a sensory mechanism (camera 24) and signalled to a control system (28) that controls the robot.

The subject matter of claim 1 differs, then, from this known method in that:

- a) a plurality of multiaxis robots are disposed stationarily along the transfer line, and
- b) the control system controls the conveyor also.

The subject matter of claim 1 is thus novel (PCT Article 33(2)).

The problems to be solved with the present invention can thus be seen in that

- a) the method allows joint control of a plurality of robots, and
- b) the method affords greater flexibility in that the speed of the conveyor can be increased or decreased depending on the machining to be done on the workpieces.

3. Claim 1: inventive step

The solution to this problem as proposed in claim 1 of the present application involves an inventive step for the following reasons (PCT Article 33(3)):

To a person skilled in the art it would not be obvious to control the robot and the conveyor with a joint control system. In the prior art the conveyor is controlled independently and the synchronization

is guaranteed only by the robot's following the movements of the workpieces by means of sensory mechanisms. The conveyor, however, cannot be adjusted to the working conditions of the robot.

4. Claim 2

Claim 2 defines the machining installation corresponding to the method as per claim 1. Mutatis mutandis the subject matter of claim 2 therefore is also novel and involves an inventive step.

5. Dependent claims

Claims 3 to 14 are dependent on claims 1 or 2 and therefore also meet the PCT requirements for novelty and inventive step.

6. Industrial applicability

Claims 1 to 14 meet the PCT requirements for industrial applicability (PCT Article 33(4)).

7. Observations preparatory to examination in the European phase

With a view to entry into the European phase, the applicant is invited to take the following observations into consideration:

7.1 Under EPC Article 54(3), D2 also qualifies as prior art. This document discloses all the features indicated in claim 2. In claim 2 the statement that "the conveyor is connected to the control system" does not necessarily mean that the control system sends control commands to the conveyor. In D2 an encoder (5) is mounted on the drive mechanism of the conveyor and connected to the control system.

Moreover, in the description in D2 (page 5, line 3)

it is mentioned that the installation can contain more than one robot.

In order to obviate an objection with regard to novelty the applicant is advised to make it clear in claim 2 that the control system controls the conveyor.

- 7.2 Documents D1 and D3 should be named in the description. The applicant should clearly identify which features of the subject matter of the independent claims are already known from these documents.
- 7.3 Independent claims 1 and 2 should be written in the two-part form according to PCT Rule 6.3(b). The features known in combination from the prior art should be included in the preamble (PCT Rule 6.3(b)(i)) and the remaining features specified in the characterizing part (PCT Rule 6.3(b)(ii)).